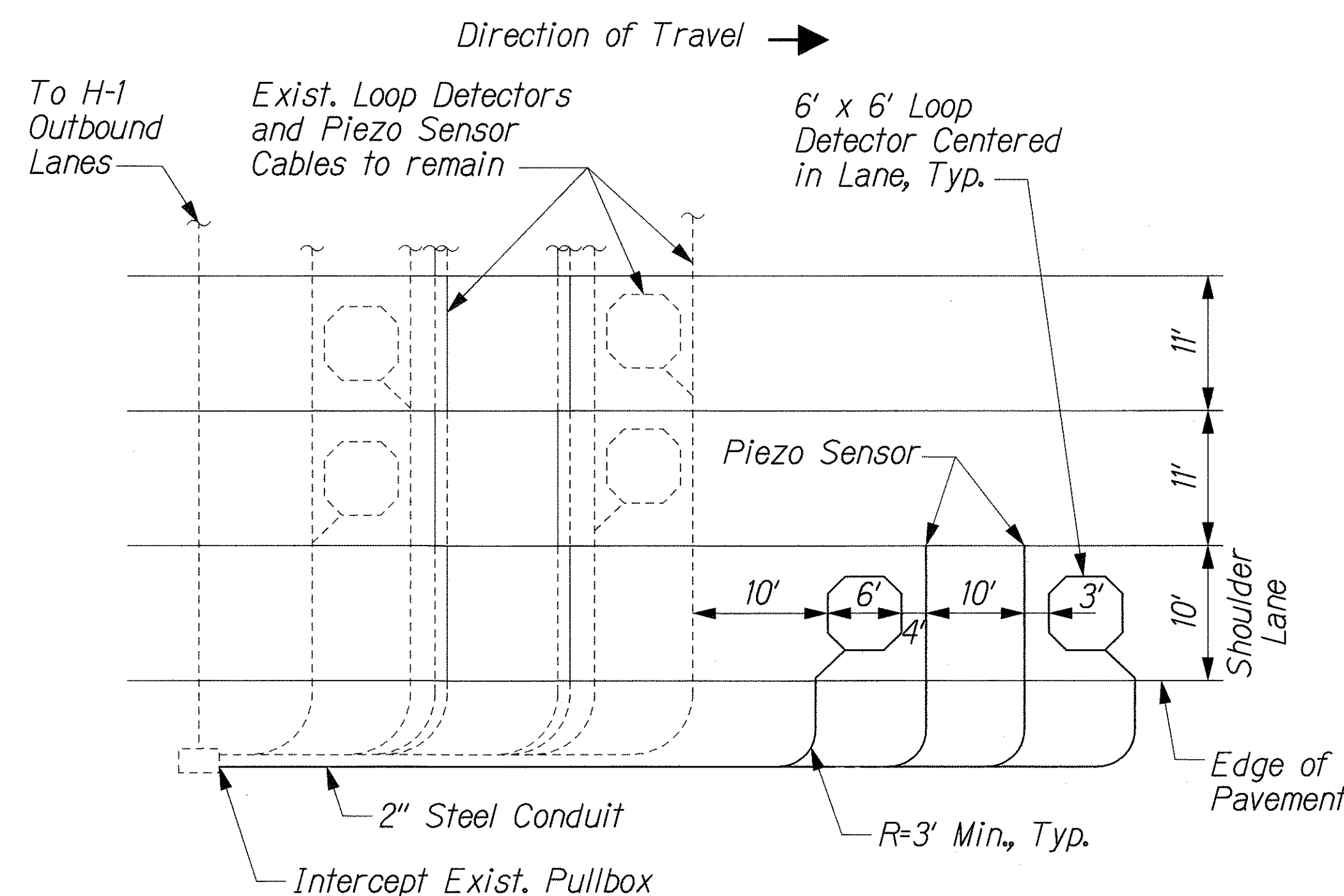
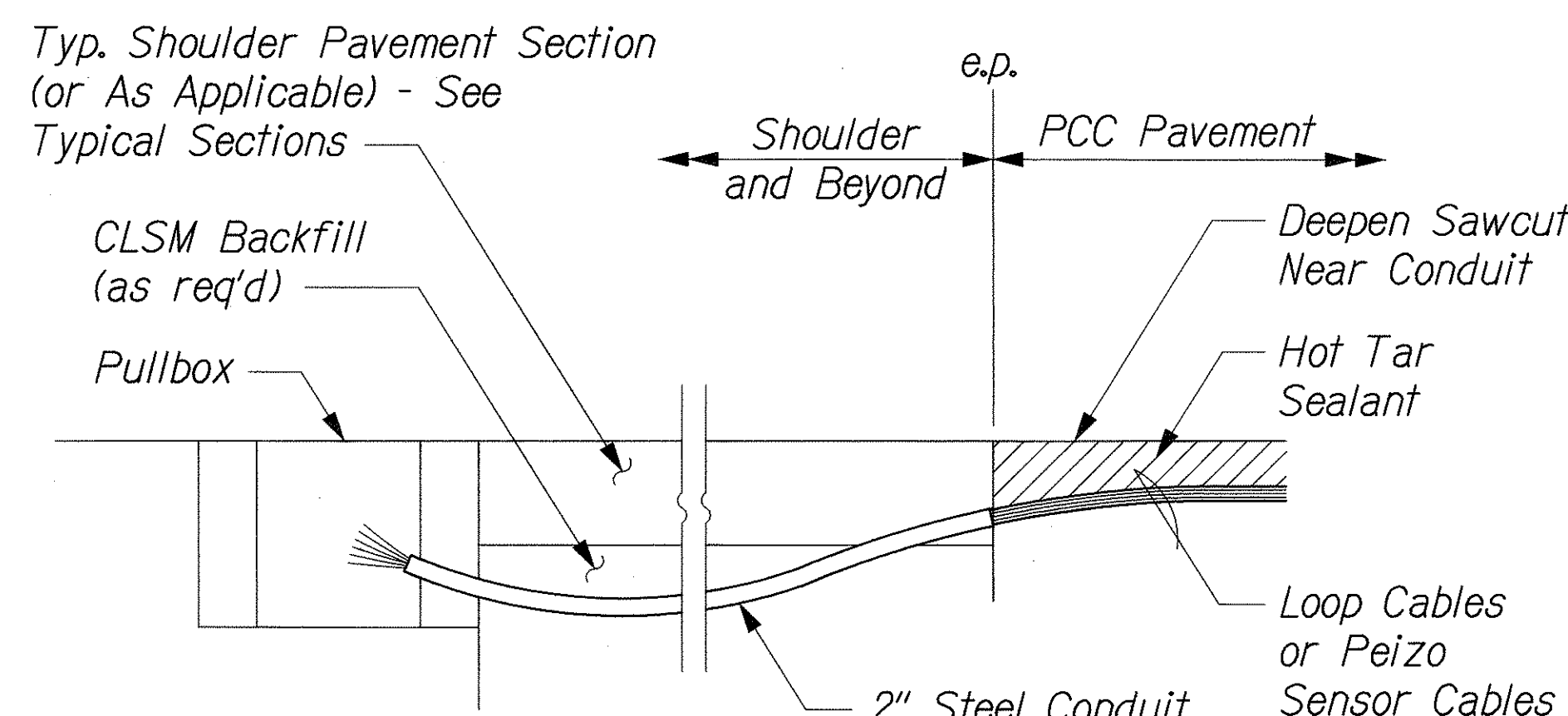


FED. ROAD DIST. NO.	STATE	FEDERAL AID PROJ. NO.	FISCAL YEAR	SHEET NO.	TOTAL SHEETS
HAWAII	HAW.	IM-HI-1(245)	2005	51	183



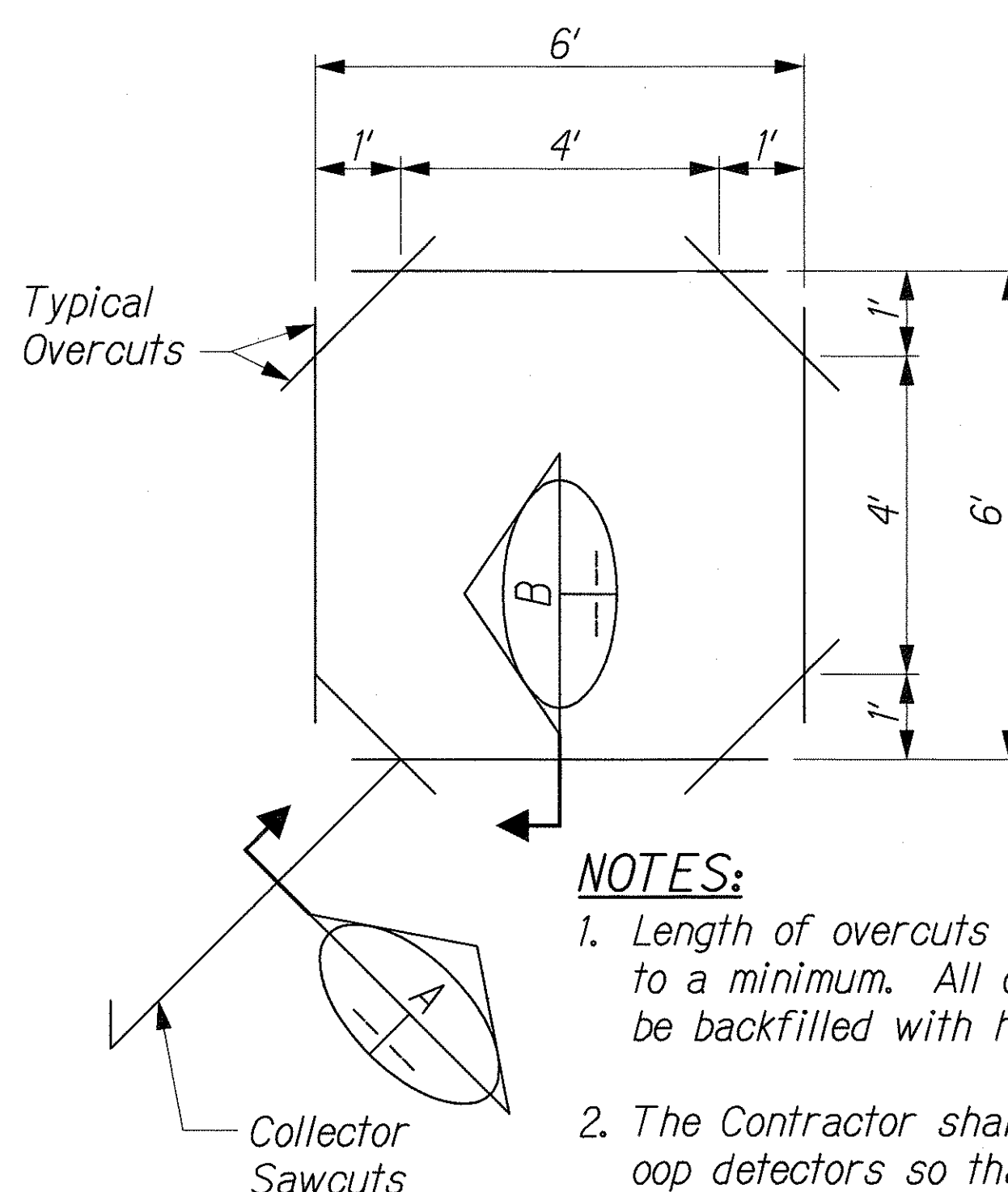
**WEIGH-IN-MOTION (WIM) SYSTEM TYPICAL LAYOUT**  
Not To Scale



**NOTES ON CONSTRUCTION AT END OF SAWCUT:**

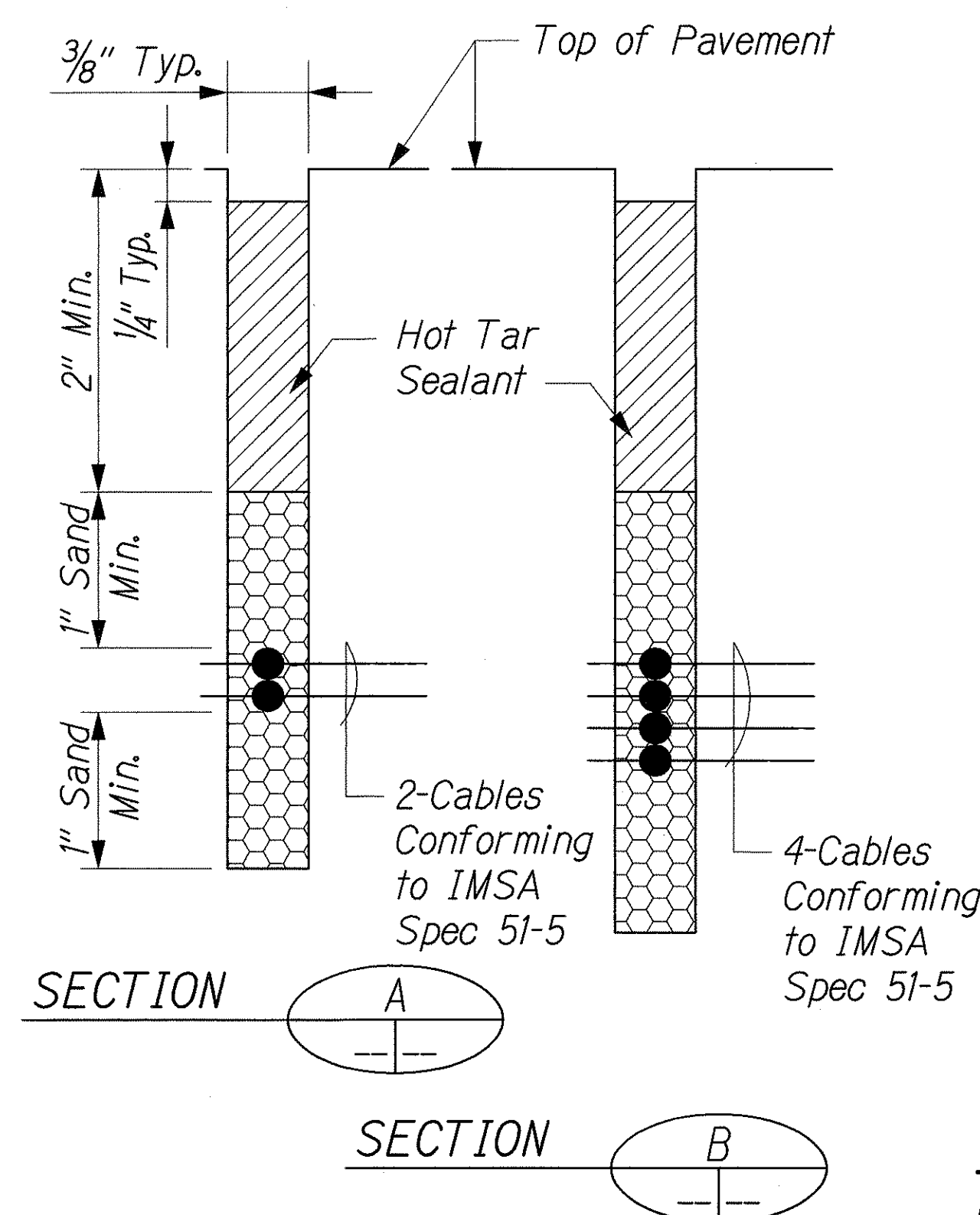
1. Seal roadway end of conduit after installation of conductors.
2. Place hot tar in sawcut.
3. Backfill over conduit with new CLSM and reconstruct pavement as required.

**DETAIL OF CONDUIT TO SAWCUT TRANSITION FOR LOOP DETECTORS AND PIEZO SENSORS**  
Not To Scale



- NOTES:**
1. Length of overcuts shall be kept to a minimum. All overcuts shall be backfilled with hot tar.
  2. The Contractor shall lay out the oop detectors so that the cutting of the pavement will not cut the existing dowels.

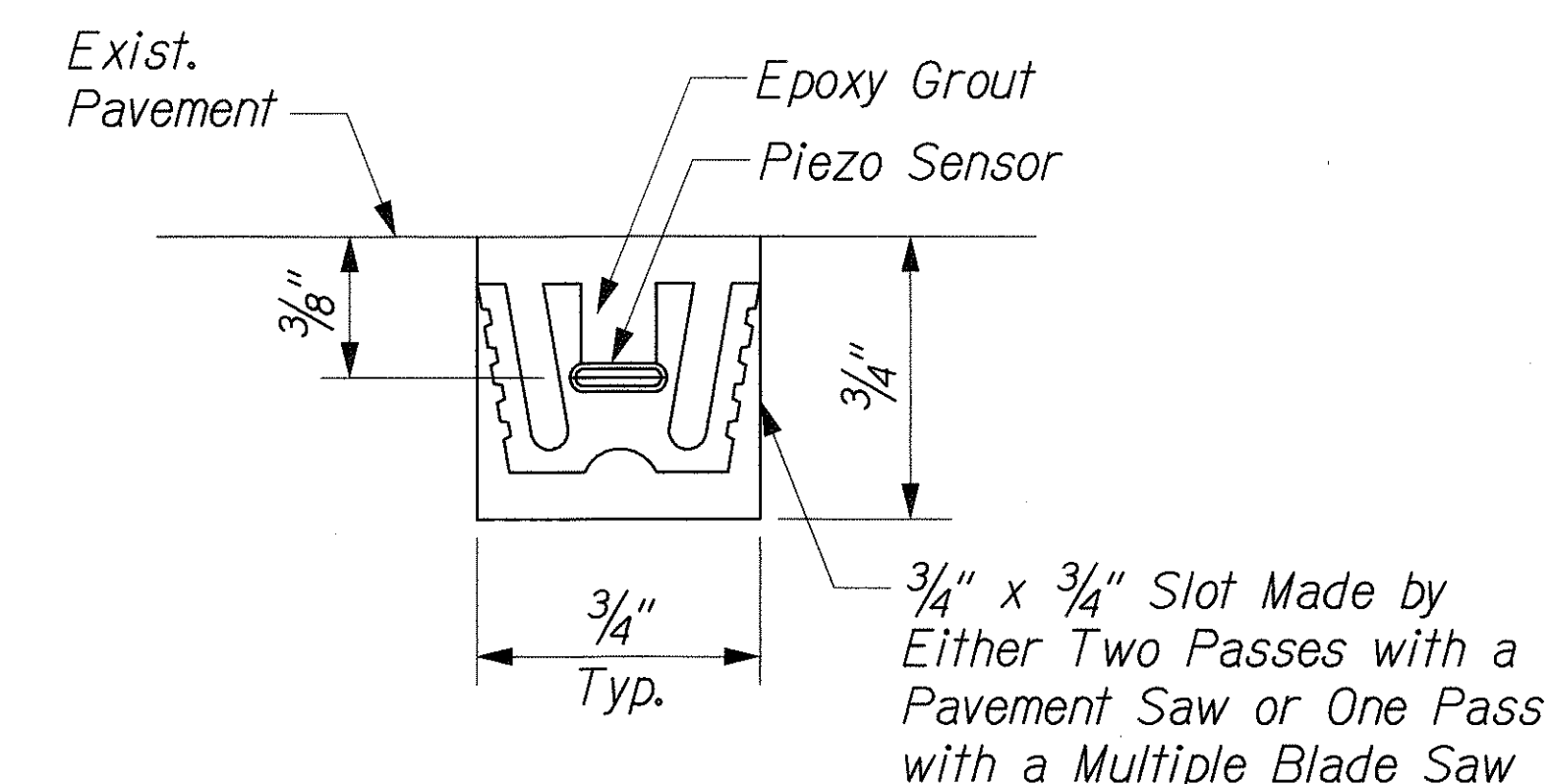
**TYPICAL SENSOR LOOP SAWCUT DETAIL**  
Not To Scale



**TYPICAL SENSOR LOOP WIRING DIAGRAM**  
Not To Scale

**NOTES:**

1. All loop and piezo lead in cables shall be pulled through the existing WIM system conduits to the existing Model 332 WIM controller cabinet located at Sta. 136+50±, o/s Lt. on the Westbound H-1 slope. Once drawn, they shall be integrated into the existing WIM system.
2. Testing, installation, connection, and calibration of the additional piezo and loop sensors shall be supervised and or performed by an authorized representative of the WIM system manufacturer. All labor and travel expenses for said representative shall be incidental to the installation of the additional sensors.
3. The Contractor shall note that additional pull lines have been placed within the existing conduits expressly for the installation of the additional sensors. However, the Contractor shall not use these pull lines for the pulling of the lead in cables. Rather they shall be used to draw new pull lines that shall then be used for the installation of the sensor lead ins.
4. Two (2) additional pull lines shall be drawn through and left in the existing WIM conduit for future use.
5. All piezo sensors shall be tested according to the specifications before and after installation.
6. All piezo sensors shall be BL Class 1 Type and rated for use in WIM systems.
7. Sensor spacings shall match those of the existing sensors as they are in the field.
8. The Contractor shall test and calibrate the entire WIM system per Section 696.03(D) to verify functionality of the new sensors, as well as the integrity of the existing sensors. All costs incurred as a result of testing and calibration of the WIM system shall be incidental to the contract.



**PIEZO SENSOR DETAIL**  
Not To Scale

	STATE OF HAWAII DEPARTMENT OF TRANSPORTATION HIGHWAYS DIVISION
	<b>WEIGH-IN-MOTION STATION DETAILS</b>
	INTERSTATE ROUTE H-1 REHABILITATION EASTBOUND LANES
	WAI'AU INTERCHANGE TO KAIMAKANI STREET
	Scale: As Shown Date: Jan. 24, 2006